

# Q5X Laser Triangulation Sensor with Dual Mode for Jam Detection



## Quick Start Guide

*Class 2 laser CMOS sensor with dual outputs. Patent pending.*

This guide is designed to help you set up and install the Q5X Laser Triangulation Sensor with Dual Mode for Jam Detection. For complete information on programming, performance, troubleshooting, dimensions, and accessories, please refer to the Instruction Manual at [www.bannerengineering.com](http://www.bannerengineering.com). Search for p/n 218902 to view the Instruction Manual. Use of this document assumes familiarity with pertinent industry standards and practices.



### WARNING:

- **Do not use this device for personnel protection**
- Using this device for personnel protection could result in serious injury or death.
- This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A device failure or malfunction can cause either an energized (on) or de-energized (off) output condition.

## Features

The Q5X has three major features.

Figure 1. Q5X Features



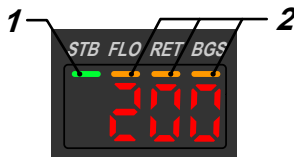
1. Two output indicators (amber)
2. Display
3. Buttons

## Display and Indicators

The display is a 4-digit, 7-segment LED. Run mode is the primary view displayed.

For JRET, JBGS, 2-pt, BGS, FGS, and DYN TEACH modes, the display shows the current distance to the target in centimeters. For Dual TEACH mode, the display shows the percentage matched to the taught reference surface. A display value of **999P** indicates the sensor has not been taught.

Figure 2. Display in Run Mode



1. Stability Indicator (STB—Green)
2. Active TEACH Indicators
  - FLO—Amber
  - RET—Amber
  - BGS—Amber



**Output Indicator**

- On—Output is on
- Off—Output is off

**Stability Indicator (STB)**

- On—Stable signal within the specified sensing range
- Flashing—Marginal signal (low excess gain), the target is outside the limits of the specified sensing range, or a multiple peak condition exists
- Off—No target detected within the specified sensing range

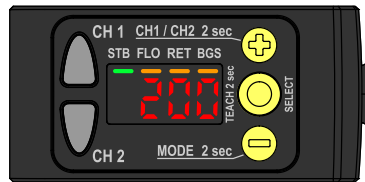
**Active TEACH Indicators (FLO, RET, BGS)**

- RET on—Jam Retroreflective TEACH mode selected (default)
- BGS on—Jam Background Suppression TEACH mode selected
- RET and BGS on—Foreground suppression TEACH mode selected
- BGS and FLO on—Background suppression TEACH mode selected
- FLO and RET on—Dynamic TEACH mode selected
- RET, FLO, and BGS all off—Two-point TEACH mode selected
- RET, FLO, and BGS all on—Dual TEACH mode selected

**Buttons**

Use the sensor buttons **(SELECT)(TEACH)**, **(+)(CH1/CH2)**, and **(-)(MODE)** to program the sensor.

Figure 3. Button Layout

**(SELECT)(TEACH)**

- Press to select menu items in Setup mode
- Press and hold for longer than 2 seconds to start the currently selected TEACH mode (the default is Jam Retroreflective TEACH)

**(+)(CH1/CH2)**

- Press to navigate the sensor menu in Setup mode
- Press to change setting values; press and hold to increase numeric values
- Press and hold for longer than 2 seconds to switch between Channel 1 and Channel 2

**(-)(MODE)**

- Press to navigate the sensor menu in Setup mode
- Press to change setting values; press and hold to decrease numeric values
- Press and hold for longer than 2 seconds to enter Setup mode



**Note:** When navigating the menu, the menu items loop.

**Class 2 Laser Description and Safety Information**

Read the following safety information for proper use of a Class 2 laser.

**CAUTION:**

- **Return defective units to the manufacturer.**
- Use of controls or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.
- Do not attempt to disassemble this sensor for repair. A defective unit must be returned to the manufacturer.

**CAUTION:**

- **Never stare directly into the sensor lens.**
- Laser light can damage your eyes.
- Avoid placing any mirror-like object in the beam. Never use a mirror as a retroreflective target.

**For Safe Laser Use - Class 2 Lasers**

- Do not stare at the laser.
- Do not point the laser at a person's eye.
- Mount open laser beam paths either above or below eye level, where practical.
- Terminate the beam emitted by the laser product at the end of its useful path.

Class 2 lasers are lasers that emit visible radiation in the wavelength range from 400 nm to 700 nm, where eye protection is normally afforded by aversion responses, including the blink reflex. This reaction may be expected to provide adequate protection under reasonably foreseeable conditions of operation, including the use of optical instruments for intrabeam viewing.

Low-power lasers are, by definition, incapable of causing eye injury within the duration of a blink (aversion response) of 0.25 seconds. They also must emit only visible wavelengths (400 to 700 nm). Therefore, an ocular hazard may exist only if individuals overcome their natural aversion to bright light and stare directly into the laser beam.

#### Class 2 Red Laser models with maximum range of 2000 mm: Reference IEC 60825-1:2007

Figure 4. FDA (CDRH) warning label (Class 2)



**Output:** < 1.0 mW

**Laser wavelength:** 640 to 670 nm

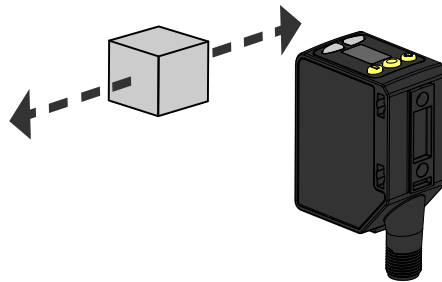
**Pulse Duration:** 20  $\mu$ s to 2 ms

## Installation

### Sensor Orientation

Optimize detection reliability and minimum object separation performance with correct sensor-to-target orientation. To ensure reliable detection, orient the sensor as shown in relation to the target to be detected.

Figure 5. Optimal Orientation of Target to Sensor



See the following figures for examples of correct and incorrect sensor-to-target orientation as certain placements may pose problems for sensing some targets. The Q5X can be used in the less preferred orientation and at steep angles of incidence and still provide reliable detection performance due to its high excess gain. For the minimum object separation distance required for each case, refer to .

Figure 6. Orientation by a wall

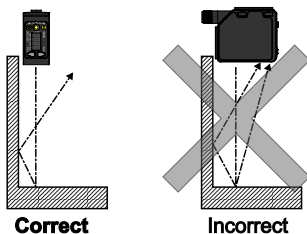


Figure 7. Orientation for a moving object

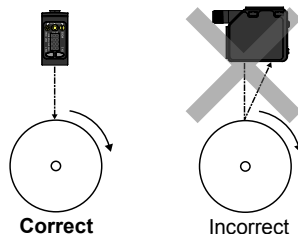


Figure 8. Orientation for a height difference

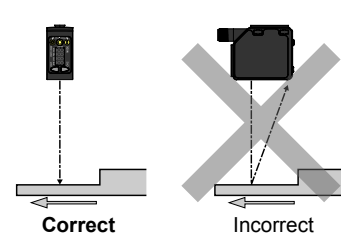
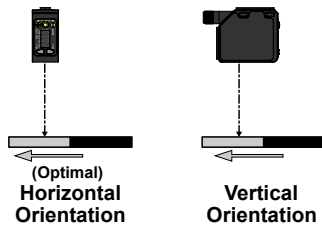
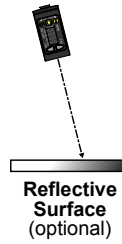


Figure 9. Orientation for a color or luster difference

Figure 10. Orientation for highly reflective target<sup>¶</sup>

## Mount the Device

1. If a bracket is needed, mount the device onto the bracket.
2. Mount the device (or the device and the bracket) to the machine or equipment at the desired location. Do not tighten the mounting screws at this time.
3. Check the device alignment.
4. Tighten the mounting screws to secure the device (or the device and the bracket) in the aligned position.

## Wiring Diagram

Figure 11. Channel 2 as PNP Discrete or PFM Output

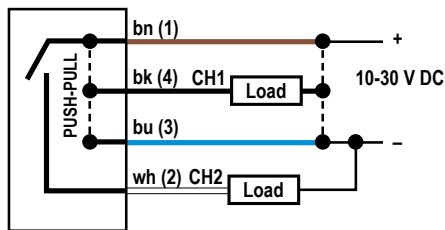
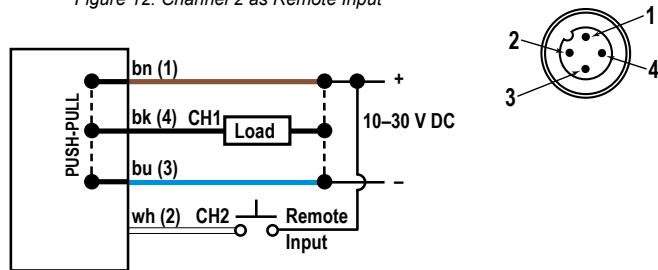


Figure 12. Channel 2 as Remote Input



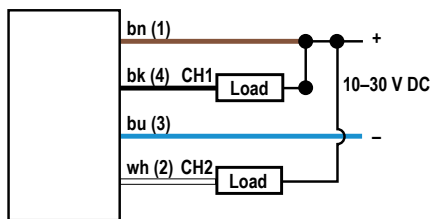
**Note:** Open lead wires must be connected to a terminal block.



**Note:** The Channel 2 wire function and polarity is user-selectable. The default for the wire is PNP output. Refer to the Instruction Manual (p/n 218902) for details regarding use as a remote input or pulse frequency modulation (PFM) output.

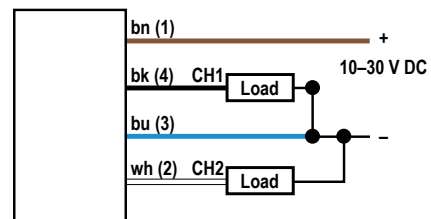
### NPN Discrete Outputs

Figure 13. Channel 1 = NPN Output, Channel 2 = NPN Output



### PNP Discrete Outputs

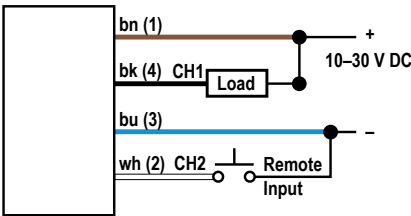
Figure 14. Channel 1 = PNP Output, Channel 2 = PNP Output



<sup>¶</sup> Applying tilt to sensor may improve performance on reflective targets. The direction and magnitude of the tilt depends on the application, but a 15° tilt is often sufficient.

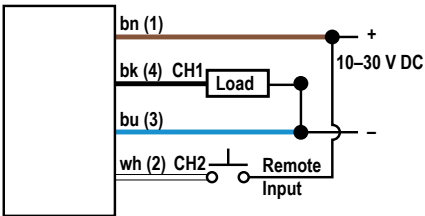
**NPN Output and Remote Input**

Figure 15. Channel 1 = NPN Output, Channel 2 = NPN Remote Input



**PNP Output and Remote Input**

Figure 16. Channel 1 = PNP Output, Channel 2 = PNP Remote Input



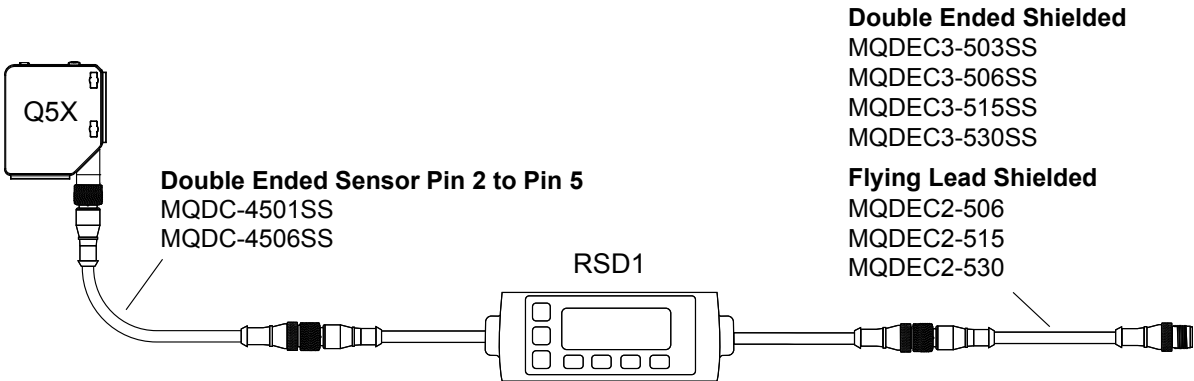
**Cleaning and Maintenance**

Clean the sensor when soiled and use with care.  
Handle the sensor with care during installation and operation. Sensor windows soiled by fingerprints, dust, water, oil, etc. may create stray light that may degrade the peak performance of the sensor. Blow the window clear using filtered, compressed air, then clean as necessary using only water and a lint-free cloth.

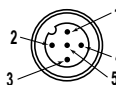
**Connecting to RSD1**

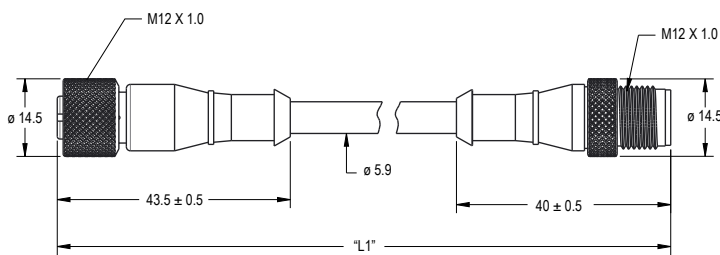
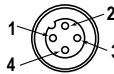
The following diagram depicts the connection of the Q5X to the optional RSD1 accessory.

Figure 17. Q5X to RSD1

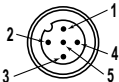
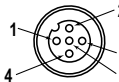
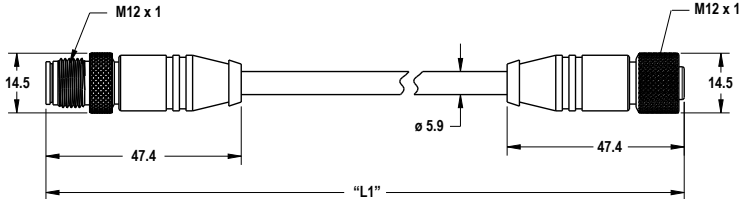


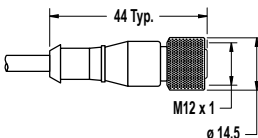
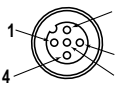
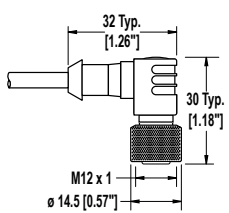
Use these cordsets to connect the RSD1 to the Q5X sensor.

4-Pin Female and 5-Pin Male Threaded M12 Cordset—Double Ended				
Model	Length "L1"	Style	Pinout	
MQDC-4501SS	0.30 m (0.98 ft)	Female Straight/ Male Straight	Male	
MQDC-4506SS	1.83 m (6.00 ft)		<div><div>1 = Brown 2 = Not Used 3 = Blue 4 = Black 5 = White</div></div>	

4-Pin Female and 5-Pin Male Threaded M12 Cordset—Double Ended			
Model	Length "L1"	Style	Pinout
			<p>Female</p>  <p>1 = Brown 2 = White 3 = Blue 4 = Black</p>

Use these cordsets to connect the RSD1 to any PLC or IO block.








5-Pin Male Threaded and 5-Pin Female Quick Disconnect M12 Cordset with Shield—Double Ended				
Model	Length "L1"	Style	Pinout (Male)	Pinout (Female)
MQDEC3-503SS	0.91 m (2.99 ft)	Female Straight/Male Straight		
MQDEC3-506SS	1.83 m (6 ft)			
MQDEC3-515SS	4.58 m (15 ft)			
MQDEC3-530SS	9.2 m (30.2 ft)			
			<div>1 = Brown 2 = White 3 = Blue</div> <div>4 = Black 5 = Gray</div>	

5-Pin Threaded M12 Cordsets with Shield—Single Ended					
Model	Length	Style	Dimensions	Pinout (Female)	
MQDEC2-506	2 m (6.56 ft)	Straight		 <p>1 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray</p>	
MQDEC2-515	5 m (16.4 ft)				
MQDEC2-530	9 m (29.5 ft)				
MQDEC2-550	15 m (49.2 ft)	Right-Angle			
MQDEC2-506RA	2 m (6.56 ft)				
MQDEC2-515RA	5 m (16.4 ft)				
MQDEC2-530RA	9 m (29.5 ft)				
MQDEC2-550RA	15 m (49.2 ft)				

## Button Map from RSD1 to Sensor

The sensor may be optionally connected to the Banner RSD1 remote display accessory. Refer to this table for the RSD1 button association with your sensor.

Table 1: Button association between the RSD1 and the Q4X/Q5X sensors

Device	Up Button	Down Button	Enter Button	Escape Button
RSD1				
Q4X and Q5X				N/A





## Sensor Programming

Program the sensor using the buttons on the sensor or the remote input (limited programming options).

In addition to programming the sensor, use the remote input to disable the buttons for security, preventing unauthorized or accidental programming changes. See the Instruction Manual, p/n 218902 for more information.

### Setup Mode

Access Setup mode and the sensor menu from Run mode by pressing and holding **MODE** for longer than 2 seconds.

Use  and  to navigate through the menu. Press **SELECT** to select a menu option and access the submenus. Use  and  to navigate through the submenus. Press **SELECT** to select a submenu option and return to the top menu, or press and hold **SELECT** for longer than 2 seconds to select a submenu option and return immediately to Run mode.

To exit Setup mode and return to Run mode, navigate to **End** and press **SELECT**.



**Note:** The number that follows a menu option, for example **lch 1**, indicates the channel that is selected. For menu items without a number (excluding submenu items), these menu options are only available from Channel 1 and the settings apply to both channels.

Figure 18. Sensor Menu Map—Channel 1

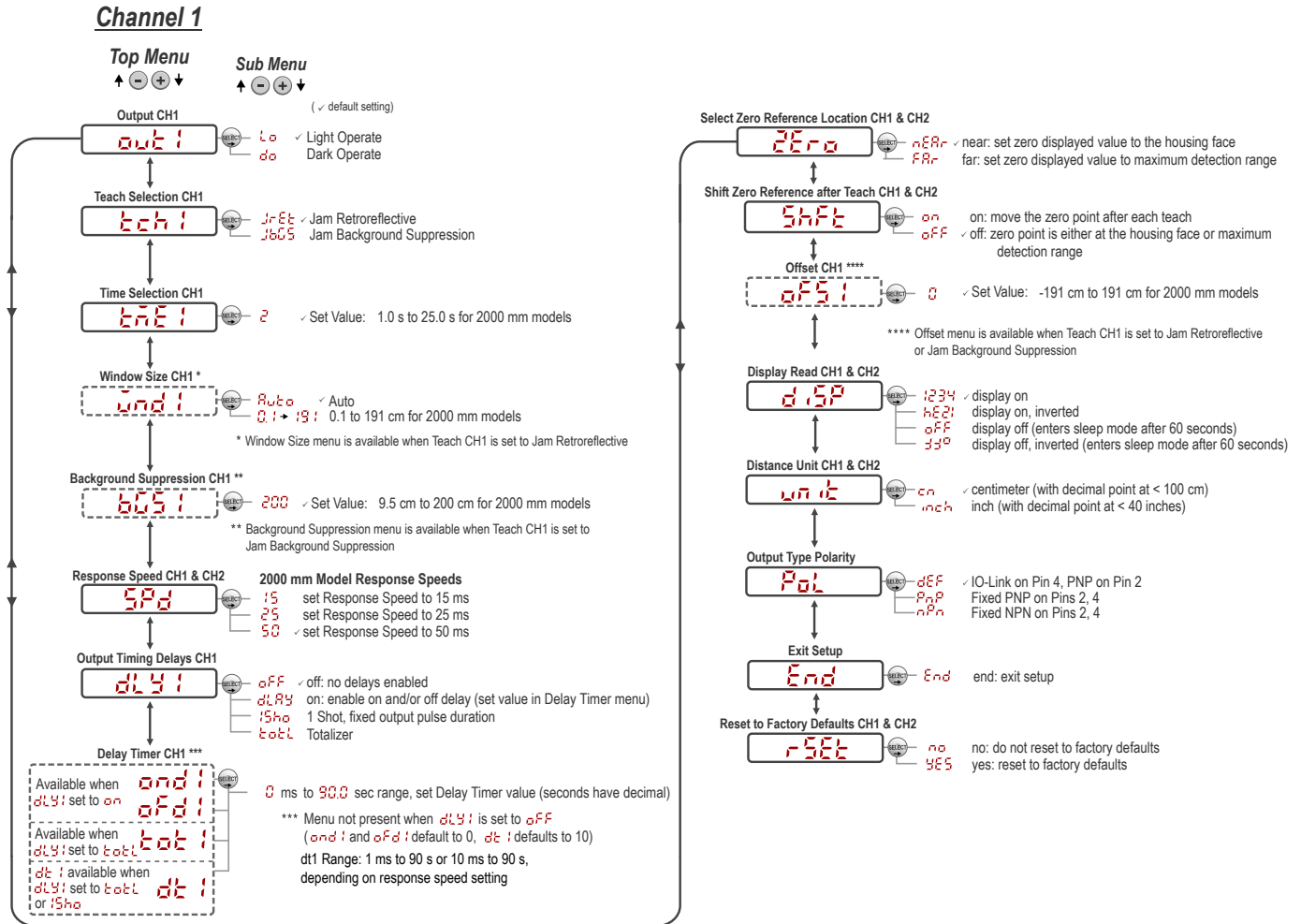
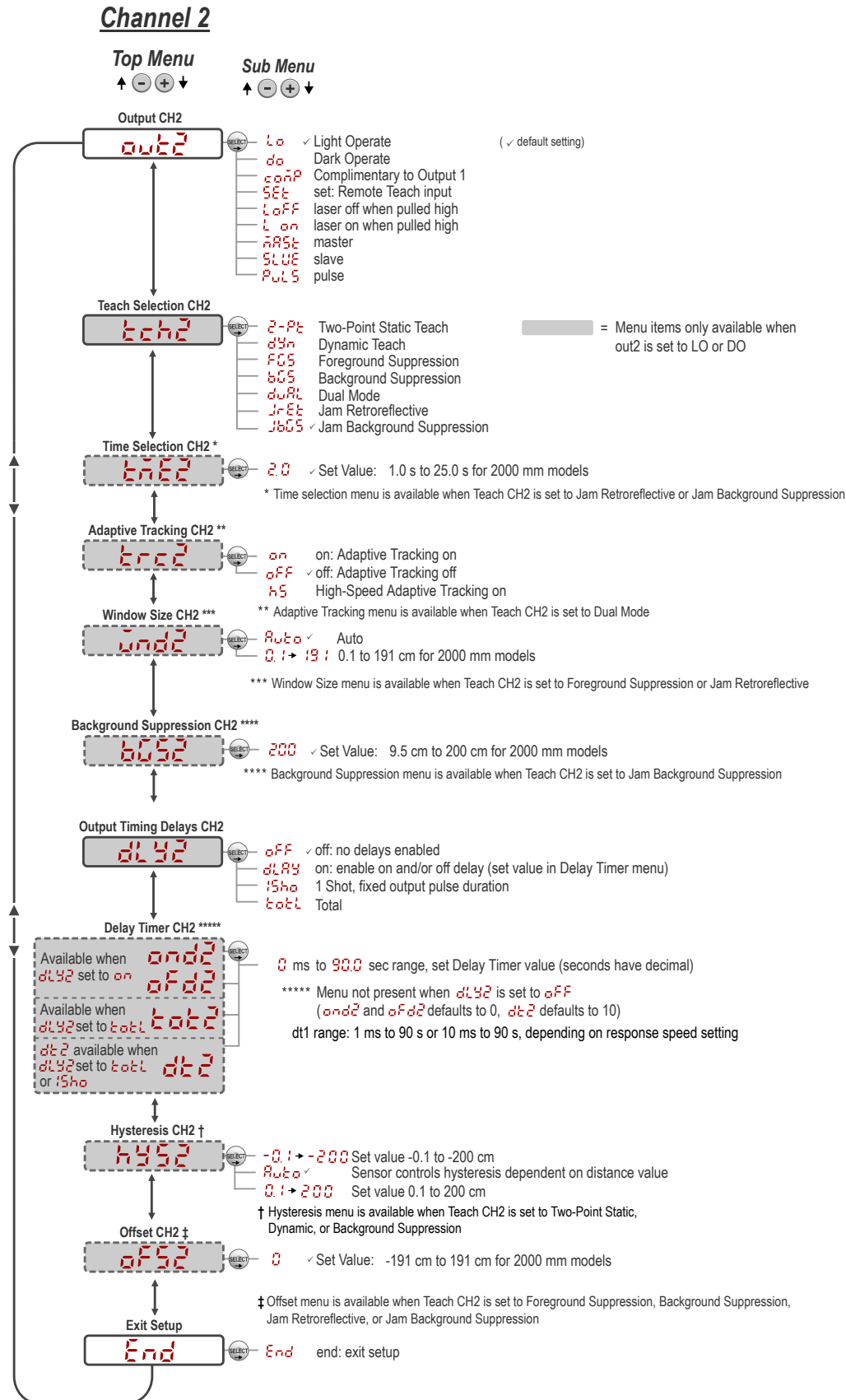




Figure 19. Sensor Menu Map—Channel 2



## Basic TEACH Instructions



Use the following instructions to teach the Q5X sensor. The instructions provided on the sensor display vary depending on the type of TEACH mode selected. Jam Retroreflective TEACH is the default TEACH mode on CH1, and Jam Background Suppression TEACH is the default TEACH mode on CH2.





1. Press and hold **TEACH** for longer than 2 seconds to start the selected TEACH mode.
2. Present the target.
3. Press **TEACH** to teach the target. The target is taught and the sensor waits for the second target, if required by the selected TEACH mode, or returns to Run mode.
4. Complete these steps only if it is required for the selected TEACH mode.
  - a) Present the second target.
  - b) Press **TEACH** to teach the target. The target is taught and the sensor returns to Run mode.

See the Instruction Manual for detailed instructions and other available TEACH modes. The TEACH modes include:

- Two-point static background suppression **2-PT** —Two-point TEACH sets a single switch point. The sensor sets the switch point between two taught target distances, relative to the shifted origin location.
- Dynamic background suppression **dyn** —Dynamic TEACH sets a single switch point during machine run conditions. The sensor takes multiple samples and the switch point is set between the minimum and the maximum sampled distances.
- One-point window (foreground suppression) **FGS** —One-point window sets a window (two switch points) centered around the taught target distance.
- One-point background suppression **BGS** —One-point background suppression sets a single switch point in front of the taught target distance. Objects beyond the taught switch point are ignored.
- Dual intensity + distance **dual** —Dual mode records the distance and amount of light received from the reference surface. See [Dual Mode Reference Surface Considerations](#) on p. 13 for more information about selecting a reference surface. The output switches when an object passing between the sensor and the reference surface changes the perceived distance or amount of returned light.
- Jam retroreflective **JRET** —Jam retroreflective TEACH mode is an extension of Dual Mode optimized for jam detection when a background is present. This mode sets a window with two switch points centered around the taught target distance. Measurements with valid intensity inside this window are qualified as not jammed. An independent jam range (RNG) value is set which defines the minimum movement required, which in combination with an automatically determined intensity threshold, determines that an object is moving (not jammed). A Loss of Signal for the user-defined time is treated as a jam.
- Jam background suppression **JBGS** —Jam background suppression TEACH mode is an extension of Dual Mode optimized for jam detection when no background is present. This mode sets a background suppression point in front of the taught target distance. Measurements with a valid intensity inside this window are qualified as not jammed. An independent jam range (RNG) value is set by the user which defines the minimum movement required, which in combination with an automatically determined intensity threshold, determines that an object is moving (not jammed). A Loss of Signal condition is not treated as a jam.

## Manual Adjustments

Manually adjust the sensor switch point using the  and  buttons.

1. From Run mode, press either  or  one time. The selected channel displays briefly, then the current setting value flashes slowly.
2. Press  to increase the setting or  to decrease the setting. After 1 second of inactivity, the new setting value flashes rapidly, the new setting is accepted, and the sensor returns to Run mode.





**Note:** When JRET or JBGS TEACH modes are selected, the manual adjustment is used to adjust the RNG value, the minimum distance of movement required to determine an object is moving (not jammed).



**Note:** When FGS TEACH mode is selected, manual adjustment moves both sides of the symmetrical threshold window simultaneously, expanding and collapsing the window size. Manual adjustment does not move the center point of the window.



**Note:** When Dual TEACH mode is selected, after the TEACH process is completed, use the manual adjustment to adjust the sensitivity of the thresholds around the taught reference point. The taught reference point is a combination of the measured distance and returned signal intensity from the reference target. Manual adjustment does not move the taught reference point, but pressing  increases the sensitivity, and pressing  decreases the sensitivity. When re-positioning the sensor or changing the reference target, re-teach the sensor.

## Locking and Unlocking the Sensor Buttons

Use the lock and unlock feature to prevent unauthorized or accidental programming changes.

Three settings are available:

- **uLoc** —The sensor is unlocked and all settings can be modified (default).
- **Loc** — The sensor is locked and no changes can be made.
- **OLoc** —The switch point value can be changed by teaching or manual adjustment, but no sensor settings can be changed through the menu.

When in **Loc** mode, **Loc** displays when the **(SELECT)(TEACH)** button is pressed. The switch point displays when **(+)(CH1/CH2)** or **(-)(MODE)** are pressed, but **Loc** displays if the buttons are pressed and held.

When in **OLoc** mode, **Loc** displays when **(+)(CH1/CH2)** or **(-)(MODE)** are pressed and held. To access the manual adjust options, briefly press and release **(+)(CH1/CH2)** or **(-)(MODE)**. To enter TEACH mode, press the **(SELECT)(TEACH)** button and hold for longer than 2 seconds.

To enter **Loc** mode, hold **+** and press **-** four times. To enter **OLoc** mode, hold **+** and press **-** seven times. Holding **+** and pressing **-** four times unlocks the sensor from either lock mode and the sensor displays **uLoc**.

## Specifications

### Sensing Beam

Visible red, Class 2 laser, 650 nm

### Supply Voltage (Vcc)

10 to 30 V DC (Class 2 supply) (10% max ripple within limits)

### Power and Current Consumption, exclusive of load

< 1 W

### Sensing Range

95 mm to 2000 mm (3.74 in to 78.74 in)

### Output Configuration

Channel 1: Push/pull output, configurable PNP or NPN output  
Channel 2: Multi-function remote input/output, configurable PNP or NPN, or pulse frequency modulated output

### Output Rating

Current rating: 50 mA maximum

Black wire specifications per configuration		
Push/Pull	Output High:	$\geq V_{\text{supply}} - 2.5 \text{ V}$
	Output Low:	$\leq 2.5 \text{ V}$
PNP	Output High:	$\geq V_{\text{supply}} - 2.5 \text{ V}$
	Output Low:	$\leq 1 \text{ V}$ (loads $\leq 1 \text{ Meg}\Omega$ )
NPN	Output High:	$\geq V_{\text{supply}} - 2.5 \text{ V}$ (loads $\leq 50 \text{ k}\Omega$ )
	Output Low:	$\leq 2.5 \text{ V}$

White wire specifications per configuration		
PNP	Output High:	$\geq V_{\text{supply}} - 2.5 \text{ V}$
	Output Low:	$\leq 2.5 \text{ V}$ (loads $\leq 70 \text{ k}\Omega$ )
NPN	Output High:	$\geq V_{\text{supply}} - 2.5 \text{ V}$ (loads $\leq 70 \text{ k}\Omega$ )
	Output Low:	$\leq 2.5 \text{ V}$

### Boresighting

$\pm 43 \text{ mm}$  at 2000 mm

### Response Speed

User selectable: 15, 25, or 50 ms

### Delay at Power Up

< 2.5 s

### Maximum Torque

Side mounting: 1 N·m (9 in·lbs)

### Ambient Light Immunity

Up to 5000 lux at 1000 mm  
Up to 2000 lux at 2000 mm

### Connector

Integral 4-pin M12 male quick disconnect

### Construction

Housing: ABS  
Lens cover: PMMA acrylic  
Lightpipe and display window: polycarbonate

### Temperature Effect (Typical)

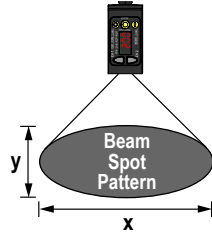
< 0.5 mm/°C at < 500 mm  
< 1.0 mm/°C at < 1000 mm  
< 2.0 mm/°C at < 2000 mm

### Discrete Output Distance Repeatability

Distance (mm)	Repeatability
95 to 300	$\pm 0.5 \text{ mm}$
300 to 1000	$\pm 0.25\%$
1000 to 2000	$\pm 0.5\%$

### Supply Protection Circuitry

Protected against reverse polarity and transient overvoltages

**Beam Spot Size**

Distance (mm)	Size (x × y) (mm)
100	2.6 × 1.5
1000	4.2 × 2.5
2000	6 × 3.6

Beam spot size is calculated as 1.6 times the  $D4\sigma$  measured value

**Required Overcurrent Protection**

**WARNING:** Electrical connections must be made by qualified personnel in accordance with local and national electrical codes and regulations.

Overcurrent protection is required to be provided by end product application per the supplied table.

Overcurrent protection may be provided with external fusing or via Current Limiting, Class 2 Power Supply.

Supply wiring leads < 24 AWG shall not be spliced.

For additional product support, go to [www.bannerengineering.com](http://www.bannerengineering.com).

Supply Wiring (AWG)	Required Overcurrent Protection (Amps)
20	5.0
22	3.0
24	2.0
26	1.0
28	0.8
30	0.5

**Remote Input**

Allowable Input Voltage Range: 0 to  $V_{supply}$

Active High (internal weak pull-down): High state > ( $V_{supply} - 2.25$  V) at 2 mA maximum

Active Low (internal weak pull-up): Low state < 2.25 V at 2 mA maximum

**Application Note**

For optimum performance, allow 10 minutes for the sensor to warm up

**Environmental Rating**

IP67 per IEC60529

**Vibration**

MIL-STD-202G, Method 201A (Vibration: 10 Hz to 55 Hz, 0.06 inch (1.52 mm) double amplitude, 2 hours each along X, Y and Z axes), with device operating

**Shock**

MIL-STD-202G, Method 213B, Condition I (100G 6x along X, Y, and Z axes, 18 shocks), with device operating

**Operating Conditions**

-10 °C to +50 °C (+14 °F to +122 °F)

35% to 95% relative humidity

**Storage Temperature**

-25 °C to +70 °C (-13 °F to +158 °F)

**Certifications**

Class 2 power

UL Environmental Rating: Type 1

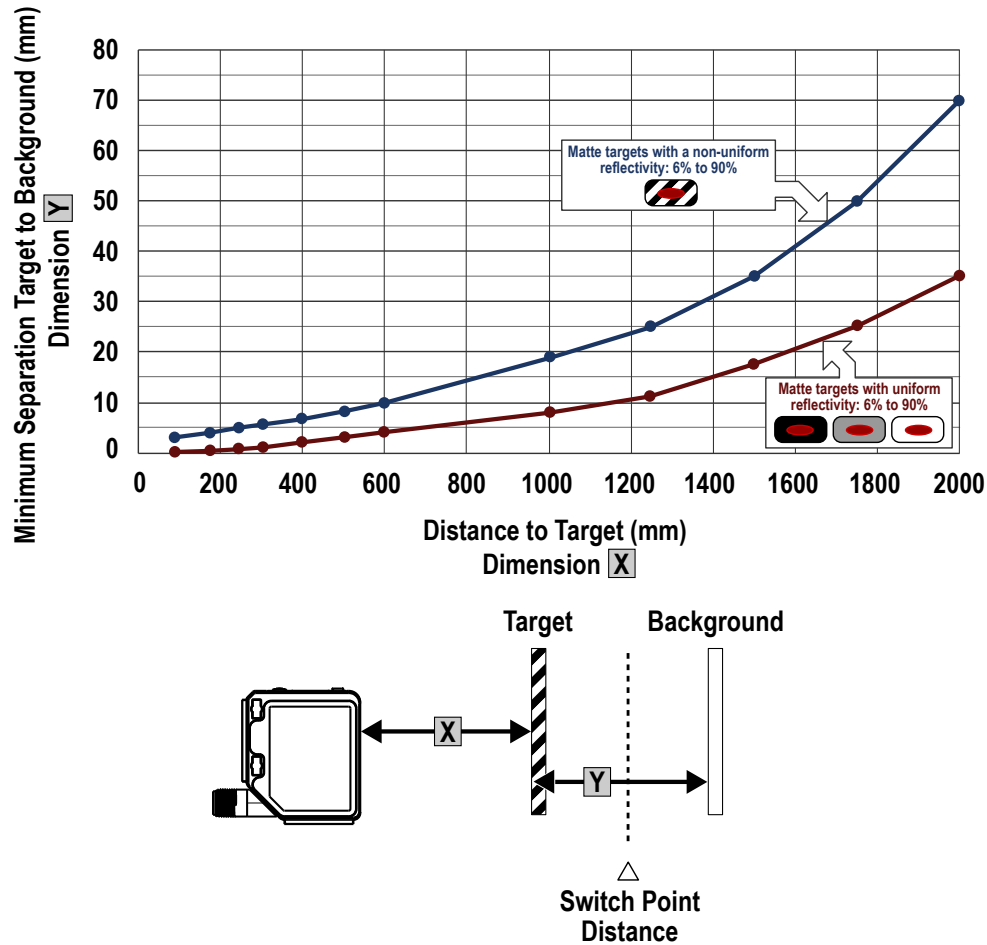
**Excess Gain**

	Excess Gain Using a 90% White Card <sup>2</sup>			
Response Speed (ms)	at 100 mm	at 500 mm	at 1000 mm	at 2000 mm
15	725 (225)	250 (75)	70 (25)	15 (6)
25	1250 (800)	450 (250)	125 (70)	30 (15)
50	2500 (1250)	900 (450)	250 (125)	60 (30)

<sup>2</sup> Standard excess gain available in 15, 25, and 50 ms response speeds; standard excess gain provides increase noise immunity.

## Performance Curves

Figure 20. Minimum Object Separation Distance (90% to 6% reflectance)



## Dual Mode Reference Surface Considerations

Optimize reliable detection by applying these principles when selecting your reference surface, positioning your sensor relative to the reference surface, and presenting your target.

The robust detection capabilities of the Q5X allows successful detection even under non-ideal conditions in many cases. Typical reference surfaces are metal machine frames, conveyor side rails, or mounted plastic targets. Contact Banner Engineering if you require assistance setting up a stable reference surface in your application.

For detailed instructions for detecting clear or transparent objects, refer to the Instruction Manual, p/n 218902.

1. Select a reference surface with these characteristics where possible:
  - Matte or diffuse surface finish
  - Fixed surface with no vibration
  - Dry surface with no build-up of oil, water, or dust
2. Position the reference surface between 200 mm (20 cm) and the maximum sensing range.
3. Position the target to be detected as close to the sensor as possible, and as far away from the reference surface as possible.
4. Angle the sensing beam relative to the target and relative to the reference surface 10 degrees or more.

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